

Mid-Range Wireless Power Transfer at 100 MHz using Magnetically-Coupled Loop-Gap Resonators

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arXiv:2103.14798v2 [physics.app-ph] 30 Apr 2021

Abstract—We describe efficient four-coil inductive power transfer (IPT) systems that operate at 100 MHz. The magnetically-coupled transmitter and receiver were made from electrically-small and high-*Q* loop-gap resonators (LGRs). In contrast to the commonly-used helical and spiral resonators, the LGR design has the distinct advantage that electric fields are strongly confined to the capacitive gap of the resonator. With negligible fringing electric fields in the surrounding space, the IPT system is immune to interference from nearby dielectric objects, even when they are in close proximity to the transmitter and/or receiver. We experimented with both cylindrical and split-toroidal LGR geometries. Although both systems performed well under laboratory conditions, the toroidal geometry has the additional advantage that the magnetic flux is weak everywhere except within the bore of the LGR and in the space directly between the transmitter and receiver. Furthermore, we show that the toroidal LGR system can be operated efficiently at a fixed frequency for a wide range of transmitter-receiver distances. The experimental results are complimented by 3-D finite-element simulations which were used to investigate the electromagnetic field profiles and surface current density distributions. Finally, we demonstrate the use of our IPT system at powers up to 32 W and discuss possible applications.

Index Terms—Field confinement, field shaping, inductive coupling, inductive power transfer (IPT), loop-gap resonator (LGR), mid-range, wireless power transfer (WPT).

I. INTRODUCTION

Most inductive power transfer (IPT) systems use helical [1]–[6] or spiral resonators [7]–[11]. These types of resonators are easy to construct, have long free-space wavelengths λ compared to the resonator diameter d with $d/\lambda \sim 0.02$, and have high quality factors $Q \sim 10^3$ [1]. One drawback, however, is that the electric fields produced in the vicinity of these resonators can be substantial. As a result, the power transfer efficiency is susceptible to degradation due to nearby non-resonant dielectric objects. The magnetic fields, while most intense between the transmitter and receiver, also occupy the complete volume of space surrounding the system [12]–[14]. On the one hand, this magnetic field configuration allows for mid-range IPT that is to some extent omnidirectional [10], [15]. On the other hand, IPT systems

Manuscript submitted on May 4, 2021.

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using helical and spiral resonators produce near-field electromagnetic (EM) waves of strengths that, even for modest powers, quickly approach the recommended human exposure limits [16], [17].

Lorenz and coworkers have designed intricate coil geometries for spiral-type resonators that suppress losses associated with both the skin effect in conductors and the proximity effect in which the magnetic fields of adjacent windings interact with one another [18], [19]. This same group has also used their novel coil designs to reduce the electric and magnetic field strengths in the regions between the transmitter and receiver coils while simultaneously maintaining high power transfer efficiency [20]. Furthermore, in an effort to develop practical high-power IPT systems that comply with safety standards, they have proposed ferrite shield geometries that could be used to further reduce EM field strengths in the space between the transmitter and receiver [21], [22].

There are also examples of IPT systems that have been implemented using alternative resonator designs. Perhaps most notably, Chabalko *et al.* have demonstrated a system in which an entire room has been fashioned into a cavity resonator that acts as the transmitter. Power can be transferred with good efficiency to multiple devices distributed throughout the room [23], [24]. Dionigi and Mongiardo have constructed a loop resonator using a length of coaxial cable [25]. The electric fields are predominantly confined to the interior of the coaxial cable while the external magnetic field is due to surface currents on the outer conductor. Song *et al.* have coupled the magnetic dipoles induced in low-loss dielectric resonators of Mg-doped $(\text{Ba}, \text{Sr})\text{TiO}_3$ with relative permittivity $\epsilon_r \approx 10^3$ [26]. Finally, metamaterials designed to have a negative effective permeability have been used in an effort to enhance the power transfer efficiency and extend the range of magnetically-coupled wireless power transfer (WPT) systems [27]–[30].

In this paper, our objective was to develop an IPT system in which the electric fields are completely confined within the resonators and the external magnetic field is weak everywhere except in the space between transmitter and receiver. Such a system would be insensitive to the presence of nearby dielectric materials, be insensitive to nearby conductors provided that they were not directly between the two resonators, and could potentially be used to limit human exposure to RF EM fields in high-power applications.

To realize these objectives, we use magnetically-coupled loop-gap resonators (LGRs) to achieve efficient mid-range IPT for frequencies in the range of 100 MHz. The design

of LGRs is well documented [31], [32]. LGRs of various geometries have been used as electron spin resonance (ESR) spectrometers [33]–[35] and to measure the electric [36], [37] and magnetic [38]–[42] properties of a wide variety of materials. The resonator consists of a physical structure that has a cylindrical cavity split by a gap that runs the length of the cylinder. Currents on the inside surface of the cylinder generate an inductive reactance, while the electric field across the gap generates a capacitive reactance. The physical geometry of the cylinder and the gap can be designed to implement high- Q resonators. One of the advantages of LGRs is that the narrow capacitive gap desensitizes the resonator to nearby dielectric materials. The cylindrical LGR (CLGR) can also be configured as a torus to implement a toroidal LGR (TLGR) that has the additional advantage of confining the magnetic field to the interior cavity with negligible leakage to the outside [43]. The magnetic field confinement of the TLGR provides additional desensitization to nearby magnetic materials that can introduce power loss in IPT systems.

The contributions of this work were: (1) to show experimental results for an innovative IPT system that uses LGRs to efficiently couple power through a medium, (2) to show EM simulation results that demonstrate the shaping and confinement of magnetic and electric fields in the region surrounding the LGRs in an IPT configuration and to show that field confinement is significantly better using TLGRs compared to CLGRs, (3) to show experimental results that demonstrate a wide fixed-frequency spatial bandwidth that is unique to the TLGR geometry, and (4) to describe an experimental method that can be used to independently determine all three of the dominant coupling coefficients in a four-coil IPT system. We also expect that our work will stimulate new research to evaluate the potential advantages of using LGR transmitters and receivers in high-power IPT applications.

The paper is organized as follows: Section II introduces equivalent circuits and data analysis methods used to interpret the experimental results. Section III describes LGRs and emphasizes the unique characteristics that make them a good fit for IPT applications. In Section IV, detailed numerical simulations are used to investigate the EM field configurations and surface current densities of the two LGR IPT designs. Section V presents the experimental measurements and data analysis. The implications of the experimental and numerical results are discussed within the context of potential applications in Section VI. Finally, Section VII summarizes the main conclusions.

II. DATA ANALYSIS METHODS

This section describes the methods used to analyze the scattering parameter data obtained from our IPT systems. In particular, equivalent circuits are used to develop models that can be fit to reflection coefficient (S_{11}) and transmission coefficient (S_{21}) measurements. These fits are used to extract the primary coupling coefficients relevant to four-coil IPT systems. Although this paper focuses on IPT using LGR transmitters and receivers, the analysis methods presented in this section can be applied to any four-coil IPT system.

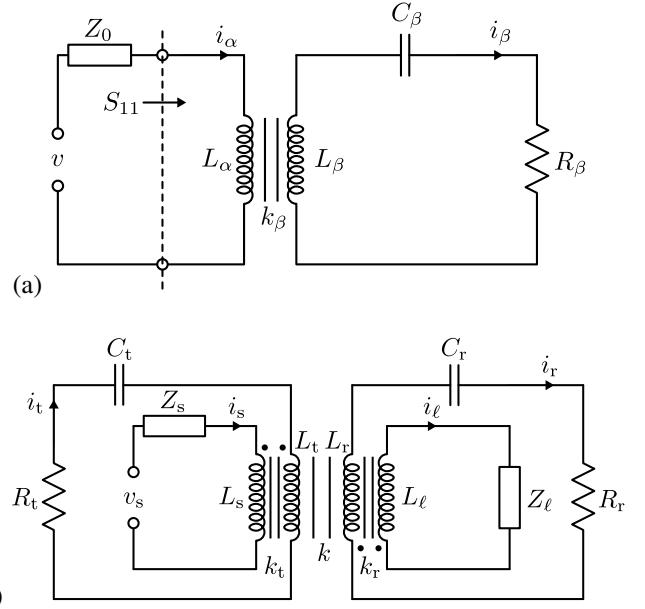


Fig. 1. Equivalent circuit models used to analyze measured scattering parameters. (a) A series resonator ($L_\beta, C_\beta, R_\beta$) coupled to an inductive loop L_α that is driven by a signal generator v with output impedance Z_0 . The dashed line represents a VNA calibration plane. The equivalent circuit models the transmit or receive resonator in an IPT system. (b) Equivalent circuit of a full IPT system. The model assumes that the source loop only couples to the transmit resonator (coupling coefficient k_t) and the load loop only couples to the receive resonator (coupling coefficient k_r). The separation distance x between the transmitter and receiver is modeled by coupling coefficient k .

A. Equivalent-Circuit Model

Figure 1(a) is an equivalent circuit model of a loop of inductance L_α magnetically coupled to a series LRC resonator. The coupling loop is driven by a signal generator with output impedance Z_0 . This circuit represents either a source ($\alpha = s$) coupling loop coupled to a resonant transmitter ($\beta = t$) or a load ($\alpha = \ell$) coupling loop coupled to a resonant receiver ($\beta = r$). In this figure, it is assumed that the transmitter and receiver have been isolated from one another. The relevant coupling coefficient k_β is determined from the mutual inductance $M_\beta = k_\beta \sqrt{L_\alpha L_\beta}$ between L_α and L_β .

The circuit in Fig. 1(a) was first analyzed in [44] and subsequently used to calculate the reflection coefficient S_{11} at the signal generator reference plane [41]. S_{11} can be expressed in terms of the effective impedance Z of the coupled resonator

$$S_{11} = \frac{Z - Z_0}{Z + Z_0}, \quad (1)$$

where the real and imaginary components of $Z = R_Z + jX_Z$ are given by:

$$R_Z = \frac{k_\beta^2 \omega L_\alpha Q_\beta \frac{\omega}{\omega_\beta} \sqrt{\frac{\omega}{\omega_\beta}}}{\frac{\omega}{\omega_\beta} + Q_\beta^2 \left(\frac{\omega}{\omega_\beta} - \frac{\omega_\beta}{\omega} \right)^2} \quad (2)$$

$$X_Z = \omega L_\alpha \left[1 - \frac{k_\beta^2 Q_\beta^2 \frac{\omega}{\omega_\beta} \left(\frac{\omega}{\omega_\beta} - \frac{\omega_\beta}{\omega} \right)}{\frac{\omega}{\omega_\beta} + Q_\beta^2 \left(\frac{\omega}{\omega_\beta} - \frac{\omega_\beta}{\omega} \right)^2} \right]. \quad (3)$$

In these expressions, $\omega_\beta^{-2} = L_\beta C_\beta$ and $Q_\beta^{-1} = R_\beta \sqrt{C_\beta/L_\beta}$ represent the unloaded (i.e. the $k_\beta \rightarrow 0$ limit) resonant frequency and quality factor of the resonator, respectively. The $\sqrt{\omega/\omega_\beta}$ factor in (2) is due to the frequency dependence of the effective resistance of the resonator which is determined by the skin depth $\delta = \sqrt{2\rho/(\mu_0\omega)}$, where ρ is resistivity, ω is angular frequency, and μ_0 is the permeability of free space [36].

Equations (1) - (3) can be used to determine $|S_{11}|$ for a resonator magnetically coupled to a loop of inductance L_α . As described in [41], L_α can be determined from a separate measurement of S_{11} taken from the coupling loop after it has been isolated from the resonator. With L_α known, fits to the measured $|S_{11}|$ spectra can be used to determine ω_β , Q_β , and k_β .

Figure 1(b) shows an equivalent circuit model of the four-coil IPT system. In the model, cross-couplings are assumed to be negligible such that the source loop couples only to the transmitting resonator (k_t) and the load loop couples only to the receiving resonator (k_r). The coupling between the transmitter and receiver is denoted k . Analyses of similar equivalent circuits have been reported previously [4], [7], [9]. In those cases, a discrete capacitance is placed in series with the coupling loops to make all four circuits resonant. We have found that the additional capacitance is not needed to tune our IPT systems. To avoid introducing additional losses, series capacitors are not used in our source and load loops.

A Kirchhoff loop analysis of the circuits in Fig. 1(b) results in the following system of equations that can be solved for the unknown current phasors I_s , I_t , I_r , and I_ℓ

$$0 = j\omega k_t \sqrt{L_s L_t} I_s - j\omega k \sqrt{L_t L_r} I_r - I_t Z_t, \quad (4)$$

$$0 = j\omega k_r \sqrt{L_\ell L_r} I_\ell - j\omega k \sqrt{L_t L_r} I_t - I_r Z_r, \quad (5)$$

$$0 = V_s + j\omega k_t \sqrt{L_s L_t} I_t - (Z_0 + j\omega L_s) I_s, \quad (6)$$

$$0 = j\omega k_r \sqrt{L_\ell L_r} I_r - (Z_0 + j\omega L_\ell) I_\ell, \quad (7)$$

where it has been assumed that $Z_s = Z_\ell \equiv Z_0$ and the quantity $Z_\beta \equiv R_\beta + j\omega L_\beta + 1/(j\omega C_\beta)$ has been defined.

For the purposes of fitting measured $|S_{21}|$ spectra, it is convenient to re-express (4) and (5) in terms of ω_β and Q_β such that

$$0 = jk_t \frac{\omega}{\omega_t} \sqrt{\frac{L_s}{L_t}} I_s - jk \frac{\omega}{\sqrt{\omega_t \omega_r}} \sqrt{\frac{Q_r}{Q_t}} I_r - (p_t + jq_t) I_t, \quad (8)$$

$$0 = jk_r \frac{\omega}{\omega_r} \sqrt{\frac{L_\ell}{L_r}} I_\ell - jk \frac{\omega}{\sqrt{\omega_t \omega_r}} \sqrt{\frac{Q_t}{Q_r}} I_t - (p_r + jq_r) I_r, \quad (9)$$

where the quantities $p_\beta \equiv Q_\beta^{-1} \sqrt{\omega/\omega_\beta}$ and $q_\beta \equiv (\omega/\omega_\beta - \omega_\beta/\omega)$ have been defined. Solving (6) - (9) for the current in the load loop I_ℓ allows one to calculate the scattering parameter $S_{21} = 2I_\ell Z_0/V_s$, which can be fit to experimental data to determine the coupling coefficient k between the transmitter and receiver.

B. Experimental Methods

In Section V-A, the efficiencies of both the CLGR- and TLGR-based IPT systems are characterized as a function of

the distance x between transmitter and receiver. For each value of x , the couplings k_t and k_r were tuned to achieve the optimal power transfer and the $|S_{21}|$ versus frequency data were recorded using a vector network analyzer (VNA). All scattering parameters reported in this paper were measured using an SDR-Kits DG8SAQ VNA.

Next, the response of the equivalent circuit described in Section II-A is compared to the response of the TLGR IPT system. The equivalent circuit parameter values were obtained from a combination of analytic and experimental results, and the method is now summarized. For each value of x , after recording the optimal $|S_{21}|$ curve, the transmitting and receiving resonators were isolated from one another without changing the positions of the source and load coupling loops. The VNA was then used to measure the $|S_{11}|$ frequency response of both the transmitter and receiver. Equations (1) - (3), based on the equivalent circuit of Fig. 1(a), were then used to determine ω_t , Q_t , k_t , ω_r , Q_r , and k_r . Finally, the $|S_{21}|$ data were fit to $2|I_\ell/V_s| Z_0$ with I_ℓ determined from (6) - (9) based on the equivalent circuit model of Fig. 1(b).

This analysis allows for a determination of the x -dependencies of k , k_t , and k_r for a tuned IPT system. It also enables an experimental investigation of the relationship between the various coupling coefficients. The coupling coefficient analysis for the TLGR IPT system is presented in Section V. A similar analysis was not done for the CLGR system because our testbed did not allow the transmitting and receiving resonators to be easily isolated from one another while maintaining constant values of k_t and k_r .

III. LOOP-GAP RESONATORS

This section describes the design of the LGRs used in the IPT systems that were investigated. A basic CLGR consists of a conducting tube with a narrow slit along its length [31], [32]. Shown in cross-section in Fig. 2(a), this structure can be accurately modeled as a series *LRC* circuit. As shown in Fig. 2(b), signals can be inductively coupled into and out of the LGR bore using coupling loops. The coupling loops are single-turn inductors that are made by short-circuiting the center conductor of a coaxial cable to its outer conductor [44]. Multi-turn inductive coupling loops can also be used when higher inductance is required. The coupling strength between the coupling loop and nearby CLGR can be easily tuned by adjusting the distance between the two.

The dimensions of the CLGRs used in our work, given in Fig. 2, were chosen such that $w \approx (\sqrt{2} - 1) r_0$ which minimizes the resonant frequency f_0 for a fixed outer diameter $d_c = 2(r_0 + w)$. In the CLGR design, the quality factor is limited by losses due to radiated magnetic power. Although radiative effects can be suppressed by surrounding the resonator by a concentric conducting cylinder [31], [36], bulky shields can be impractical in many applications. A TLGR can be made by joining two ends of a CLGR such that the bore of the resonator forms a torus. The toroidal geometry confines the magnetic fields within the resonator bore such that high Q 's are achieved without requiring EM shields [43]. A schematic of the TLGR cross-section is shown in Fig. 2(c). The figure

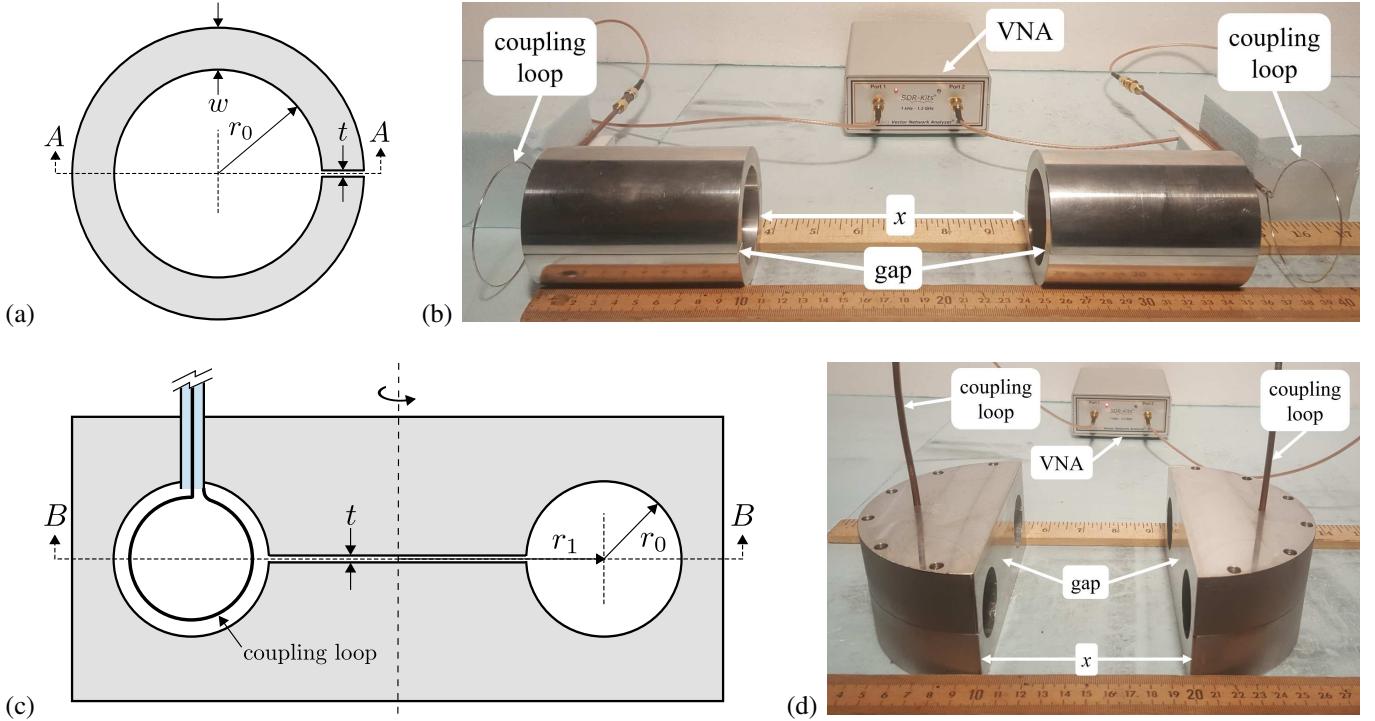


Fig. 2. (a) Scale drawing of the CLGR cross-section with the gap size t exaggerated by a factor of 10^3 . The dimensions of the CLGR are $r_0 = 2.54$ cm, $w = 1.02$ cm, $t = 102\mu\text{m}$, and its length is $\ell = 10.16$ cm. (b) Photograph of the IPT experimental setup using identical CLGRs made from aluminum. The source and load coupling loops, made from semi-rigid coaxial cable and attached to the two ports of the VNA, are positioned to achieve optimal power transfer efficiency. For scale, the transmitter and receiver are separated by a distance $x = 15$ cm. (c) Scale drawing of the TLGR cross-section with the gap size t exaggerated by a factor of 10^3 . The dimensions of the TLGR are $r_0 = 1.75$ cm, $r_1 = 4.60$ cm, and $t = 102\mu\text{m}$. (d) Photograph of the IPT experimental setup using identical split-TLGRs made from aluminum. The source and load coupling loops are suspended within the bores of the TLGRs. For scale, the transmitter and receiver are separated by a distance $x = 10$ cm.

also shows a coupling loop suspended within the bore of the resonator. In this case, the coupling strength is adjusted by changing the orientation of the loop relative to the bore cross-section. The dimensions of the TLGR used in this work were chosen to satisfy $r_0 \approx 5r_1/13$ which minimizes f_0 for a given resonator size characterized by $d_t = 2(r_0 + r_1)$.

Figure 2(d) shows a pair of identical split-TLGRs used as a transmitter-receiver set in an IPT system. Because currents loop around the axis of the toroidal bore, dividing the TLGR in half does not significantly alter the distribution or flow of charge and the resonant frequency is approximately unchanged. In terms of an equivalent circuit model, dividing the resonator in half reduces the capacitance by a factor of two and increases the inductance by the same factor such that the resonant frequency $\omega_0 = 2\pi f_0 \approx 1/\sqrt{LC}$ remains unchanged.

One property that makes LGRs well-suited to IPT applications is their small electrical size. The resonant frequency of a CLGR is given by

$$f_0 \approx \frac{1}{2\pi} \frac{c}{r_0} \sqrt{\frac{t}{\pi \epsilon_r w}}, \quad (10)$$

where c is the vacuum speed of light and ϵ_r is the dielectric constant of the material filling the gap of the resonator. Using (10) to solve for the free-space wavelength $\lambda = c/f_0$, setting $w = (\sqrt{2} - 1)r_0$, and writing w and r_0 in terms of the diameter $d_c = 2(r_0 + w)$ leads to

$$\frac{d_c}{\lambda} \approx 0.66 \sqrt{\frac{t}{\epsilon_r d_c}}. \quad (11)$$

In our experiments, the resonator gap was filled with Teflon and $\epsilon_r \approx 2.1$. Using the dimensions given in Fig. 2(a), $d_c/\lambda \approx 0.017$ which is similar to the values achieved using helical and spiral resonators. Manipulating any of d_c , ϵ_r , or t to decrease f_0 will result in a decrease of the resonator size-to-wavelength ratio. A similar analysis for the TLGR leads to

$$\frac{d_t}{\lambda} \approx 2.48 \sqrt{\frac{t}{\epsilon_r d_t}} \quad (12)$$

where $d_t = 2(r_0 + r_1)$. Assuming a Teflon dielectric and using the dimensions given in Fig. 2(c) results in $d_t/\lambda \approx 0.048$. Although its size-to-wavelength ratio is several times larger than that of the CLGR, the toroidal geometry has other advantages, discussed below, that make it an attractive option for some IPT applications.

In the absence of radiative power losses, the unloaded quality factors of both the cylindrical and toroidal LGRs are approximately given by $Q_\delta \approx r_0/\delta$ [31], [36], [43]. For aluminum resonators with $f_0 \approx 100$ MHz, $r_0/\delta \sim 2000$. As mentioned above, radiative effects in CLGRs are non-negligible and result in a suppression of the net $Q = (Q_\delta^{-1} + Q_r^{-1})^{-1}$, where Q_r is the quality factor associated with radiative losses. The split-TLGRs used in our experiments, also susceptible to radiative losses, had quality factors of $\sim 10^3$ which match the values typically obtained using helical and spiral resonators operating at ~ 10 MHz. It is worth noting that, for cylindrical and toroidal LGRs designed to have

the minimum f_0 for a given d , $Q_\delta \propto (td/\epsilon_r)^{1/4}$. To the extent that LGRs can be modeled as current loops, Q_r is proportional to $(\epsilon_r d/t)^{3/2}$ [45]. This analysis suggests that $Q_r/Q_\delta = (\epsilon_r d^{5/7}/t)^{7/4}$ such that Q_r increases relative to Q_δ when the LGR resonant frequency is lowered by increasing ϵ_r or d , or by decreasing t . Even if the current-loop model is not strictly correct, the insight that the radiative effects become less important as f_0 is decreased is still expected to apply.

In both the cylindrical and toroidal LGR designs, the electric fields are strongly confined to the gap of the resonator. This is a key advantage for IPT applications because it makes the system insensitive to nearby dielectric objects, even if those objects are dynamic. It also provides an opportunity to develop systems that wirelessly transfer power through a medium with non-negligible conductivity σ , such as saltwater [46]. Filling the gap with a low-loss dielectric, or otherwise isolating the gap from the conducting medium, eliminates the power dissipation (proportional to $\sigma|E|^2$) associated with the electric fields E .

The bore of CLGRs, modeled as a single-turn inductor, produce magnetic fields that form closed loops by exiting one end of the bore and entering the opposite end. In this way, a pair of coupled CLGRs have magnetic field configurations that are qualitatively similar to those obtained in IPT systems using conventional helical and spiral resonators. Therefore, a IPT system implemented with CLGRs is expected to have similar spatial sensitivity relative to other systems implemented using helical or spiral resonators [10].

In applications that do not require omnidirectional power transfer, such as when the lateral alignment of transmitter and receiver is fixed, the split-TLGRs offer another unique advantage. The geometry ensures that, for a pair of coupled split-TLGRs, the magnetic flux is very weak everywhere except within the bores of the resonators and in the space directly between transmitter and receiver. A detailed analysis of the EM field configurations of LGR IPT systems is presented next.

IV. ELECTROMAGNETIC SIMULATIONS

Numerical simulations using a finite element solver in COMSOL were used to investigate the EM fields in LGR IPT systems. Complete models of the four-coil IPT systems were created with 50Ω ports exciting a narrow gap in the source and load coupling loops. The amplitude of the source delivers a peak voltage of 1 V to a matched port. The entire model was surrounded by a spherical boundary with a perfectly matched layer. In all simulations, we confirmed that the spherical boundary had negligible effects on the results.

The aluminum resonators were modeled with a finite resistivity of $2.65 \times 10^{-8} \Omega \text{m}$. The capacitive gap in the model was set to $102 \mu\text{m}$ to match the design value and it was filled with a lossless dielectric. Because it was difficult to accurately measure the gap size of the experimental resonators, the simulated resonant frequencies were tuned to match the experimental values by adjusting the dielectric constant of the gap material.

A simulation was set up to model an IPT link with CLGRs. The distance x between the transmit and receive CLGRs was

88.8 cm and the dielectric constant in the gap region was set to $\epsilon_r = 1.4$. The coupling loop positions were tuned to achieve critical coupling and the simulation was run at the frequency of optimum power transfer efficiency. The coupling loop diameters were 65.4 mm, the source loop-transmitter distance was 10.75 mm, the load loop-receiver distance was 13.2 mm, and the frequency was 102.1 MHz.

The simulation results for the CLGR IPT system are shown in Figs. 3(a) and (b). In Fig. 3(a), the magnitude of the electric field E is shown for a plane that passes through the centers of the CLGR gaps. The corresponding cross-section is shown as section *AA* in Fig. 2(a). The color scale in Fig. 3(a) is logarithmic to illustrate how rapidly the electric field strength decreases as one moves away from the capacitive gap. Figure 3(b) shows the corresponding magnitude of the magnetic field B for the CLGR IPT. The color scale is logarithmic and the magnetic field is strongest within the bores of the CLGRs. Outside the CLGRs, the magnetic field is weaker and extends to the surrounding space to provide magnetic coupling between the transmitter and receiver. Also note that the magnetic field extends through the capacitive gap region in the CLGRs. The gap region is at the bottom of Fig. 3(b) and the field decreases across the gap as the outer edge is approached.

Figures 3(c) and (d) show the simulated electric and magnetic field strengths for the split-TLGR IPT system. The fields are shown through section *BB* indicated in Fig. 2(c). So that direct comparisons between the CLGR and TLGR systems can be made, Figs. 3(a) and (c) and Figs. 3(b) and (d) use the same color scales. In the TLGR case, critical coupling and optimum power transfer were achieved using $x = 31$ cm, $\epsilon_r = 2.1$, and $f = 122.5$ MHz. The coupling loops had a radius of 15.5 mm and the planes of the loops were aligned with the cross-sections of the split-TLGR bores. Once again, the electric field is weak everywhere outside the gap. The corresponding magnetic field for the TLGR IPT system is shown in Fig. 3(d). Unlike the CLGR case, the magnetic field is primarily confined to the direct bore coupling region and rapidly decreases outside this region. The magnetic field strength in the region behind the split-TLGRs is approximately two orders of magnitude less than that in the space linking the bores of the pair of resonators. It is this property that makes the split-TLGRs unique among all of the other resonators currently used in IPT systems.

For the coupled CLGRs, Fig. 4(a) shows plots of E and B as a function of position along the dashed lines shown in Figs. 3(a) and (b). The electric field a distance $w = 1.02$ cm from the outside edge of the gap is more than 2.5 orders of magnitude less than the peak value of E . The magnetic field is uniform within the bore and then linearly decreases through the gap, a behavior that was first predicted by the theoretical analysis of Hardy and Whitehead in [31]. These results show that the simulations provide reliable solutions for the EM fields of the IPT models. Figure 4(b) shows the corresponding E and B plots for the TLGR system along the dashed lines of Figs. 3(c) and (d). In this case, a diagonal path was chosen to avoid extrinsic effects due to the coupling loop and the ends of the split-TLGR bore. Once again, the electric field strength

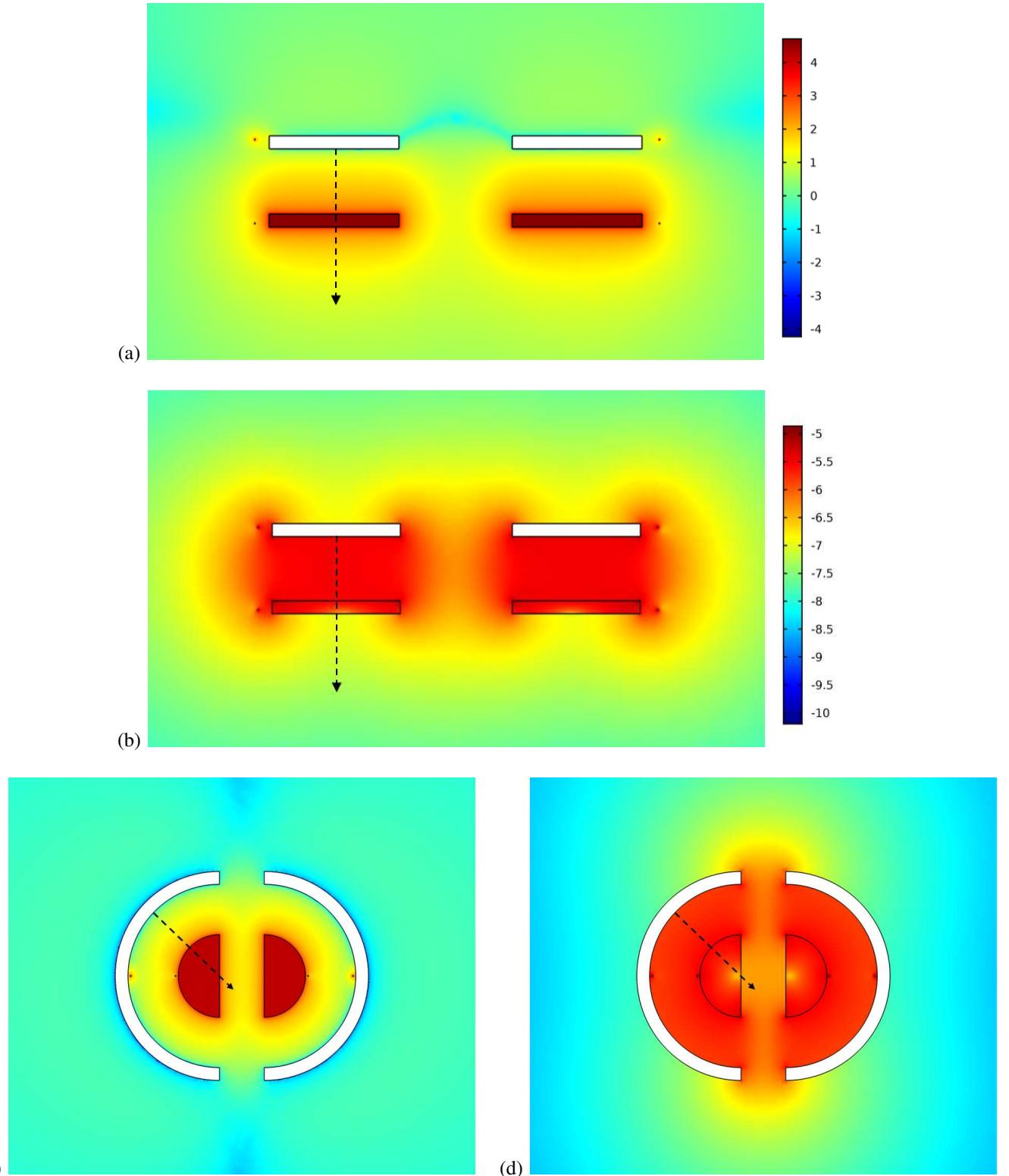


Fig. 3. The simulated (a) electric and (b) magnetic field magnitudes for a CLGR-based IPT system. The color scales are $\log E$ and $\log B$, respectively. The dashed arrows show the cut lines that were used to generate the plots in Fig. 4(a). The simulated (c) electric and (d) magnetic field magnitudes for a TLGR-based IPT system shown using logarithmic color scales. The color scales of (c) and (d) are identical to the scales used in (a) and (b), respectively. The dashed arrows show the cut lines that were used to generate the plots in Fig. 4(b).

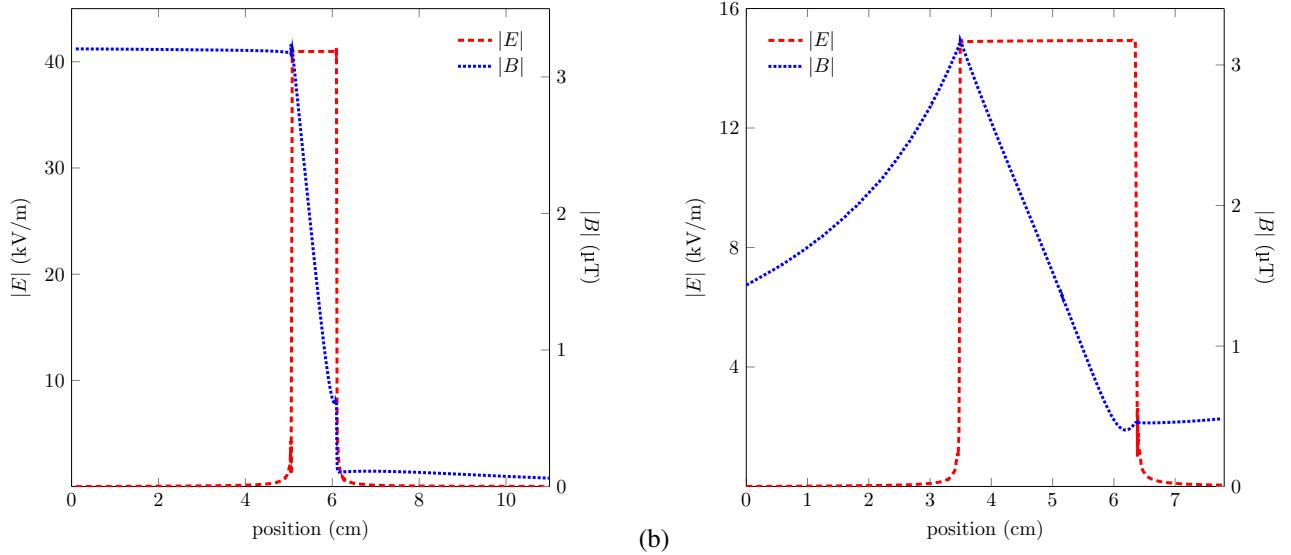


Fig. 4. The electric and magnetic field strengths as a function of position through the resonator bore and gap for coupled (a) CLGRs and (b) split-TLGRs. The paths followed to generate these plots are shown in Figs. 3(a)–(d). For both the CLGR and TLGR IPT systems, the electric field strength is very weak outside of the gap region. For the CLGR, the magnetic field strength is nearly constant through the bore and then decreases linearly through the gap. In the case of the TLGR, the magnetic field has a $1/r$ dependence through the bore and then falls off linearly through the gap.

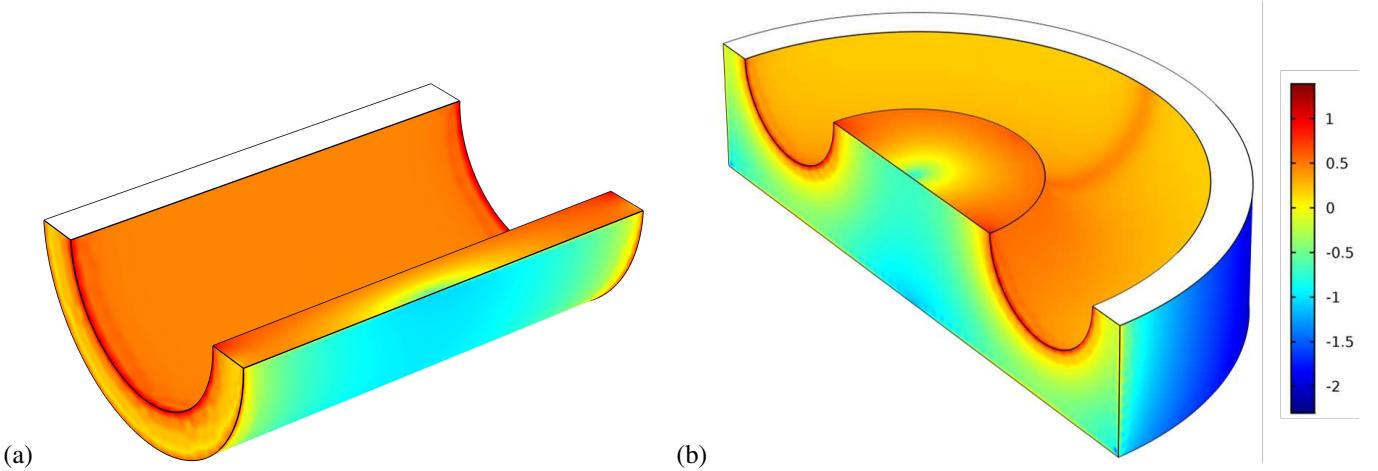


Fig. 5. Surface current density maps for the (a) CLGR and (b) TLGR IPT systems. The color scales represent $\log J_s$ and are identical for (a) and (b). For clarity, only the bottom halves of the transmitting resonators are shown. The white surfaces represent cuts through solid aluminum.

is negligible outside the gap. The magnetic field strength has a linear dependence through the gap and then falls off as $1/r$ through the bore which is characteristic of the magnetic field of a toroid.

An important observation is that the substantial magnetic flux contained within the gap of the TLGR limits the maximum possible coupling to the loop suspended within the bore. Specifically, the coupling coefficients k_t and k_r are expected to be significantly less than one, even with the plane of the loop set perpendicular to the axis of the toroidal bore (i.e. maximum coupling).

Figure 5 shows the magnitudes of the simulated surface current densities J_s on a logarithmic scale for both the CLGR and TLGR IPT systems. These figures were generated from the same simulations used to create Figs. 3 and 4. For clarity, in both (a) and (b), only the bottom halves of the transmitting resonators are shown. Identical color scales are used for the

pair of images. As expected, the surface current densities are nearly uniform along the inner surfaces of the LGR bores. Figure 5(a) shows that J_s is enhanced at ends of the CLGR bore which is where local hot spots due to Joule heating would be expected in high-power applications. For the TLGR, Fig. 5(b) shows that J_s is again largest at the ends of the bore. The surface current density is also enhanced along the outer diameter of the TLGR gap and near the midpoint of the bore where the coupling loop is suspended (not shown in the figure).

V. EXPERIMENTAL RESULTS

A. Power Transfer Efficiency Versus Distance

This section begins with an experimental comparison of the power transfer efficiency of CLGR- and TLGR-based IPT systems. First, the transmitting and receiving LGRs were set to have identical resonant frequencies such that $f_t = f_r \equiv f_0$.

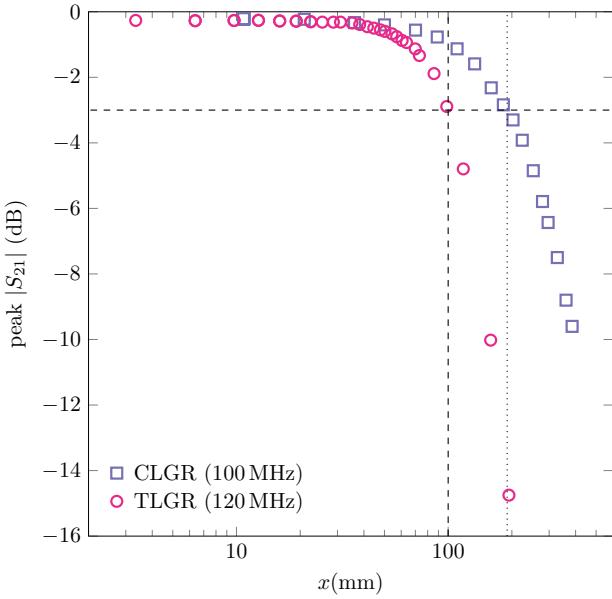


Fig. 6. Peak $|S_{21}|$ as a function of transmitter-receiver separation distance x for the CLGR and TLGR IPT systems. The horizontal dashed line is the -3 dB point and is used to define the spatial bandwidth x_0 of the IPT systems. The vertical dashed and dotted lines indicate the spatial bandwidths of the TLGR and CLGR systems, respectively.

For each resonator, the frequency was set by adjusting the fraction of the gap that was filled with Teflon. After tuning, the resonant frequencies for the CLGR and split-TLGR systems were 100 MHz and 120 MHz, respectively. Next, the distance x between the transmitter and receiver was set and the couplings k_t and k_r were adjusted for maximum power transfer efficiency.

Figure 6 shows plots of the peak $|S_{21}|$ of the tuned systems as a function of separation distance x . It is important to emphasize that the peak $|S_{21}|$ frequencies are different at each value of x in Fig. 6. Therefore, the performance suggested in the figure could only be achieved while employing a frequency tracking system. We consider fixed-frequency operation in Section V-F. At the smallest values of x , the CLGR system achieves a peak $|S_{21}| \approx -0.21\text{ dB}$ which corresponds to a power transfer efficiency of 95 %. The efficiency remains high as x is increased and then rapidly drops off after passing a critical distance x_0 which we define to be the -3 dB point. We refer to x_0 as the spatial bandwidth and, for the CLGR system, it was found to be $x_0 \approx 19.0\text{ cm}$. The roll off above x_0 is steep with $|S_{21}|$ dropping by approximately 7 dB when x doubles from 20 to 40 cm.

The peak $|S_{21}|$ versus x measurements for the TLGR system follow the same general trends found with the CLGRs. At the smallest values of x , $|S_{21}|$ peaked at -0.26 dB (94 % efficiency). The spatial bandwidth of this system was $x_0 = 10.0\text{ cm}$ and the roll off for $x > x_0$ was very steep, dropping by approximately 13.0 dB when the distance was doubled from 10 to 20 cm.

The results from Fig. 6 clearly suggest that the CLGR system outperforms the TLGR system. It has a higher spatial bandwidth and the roll off above x_0 is slower. A useful

TABLE I
FIGURE OF MERIT COMPARISON OF IPT SYSTEMS IN THE PUBLISHED LITERATURE. THE PARAMETER x_0 IS THE SPATIAL BANDWIDTH OF THE IPT SYSTEM AND s CHARACTERIZES THE SIZE OF THE TRANSMITTER/RECEIVER

Resonator Type	f_0 (MHz)	s (cm)	x_0 (cm)	x_0/s	Reference
CLGR	100	10.2	19	1.9	–
TLGR	120	12.7	10	0.79	–
helical	10.56	60	180	3.0	[1]
coaxial	30.8	20	< 60	< 3.0	[25]
dielectric	232	8.4	16	1.9	[26]
spiral	7.65	59	100	1.7	[7]
spiral	6.7	56	85	1.5	[9]
helical	16.1	15	15	1.0	[4]
coil	0.742	3.8	2.5	0.66	[5]
coil	0.7	6.4	4.0	0.63	[2]

figure of merit for IPT systems is x_0/s where s characterizes the largest dimension of the transmitter/receiver. We use s_c and s_t to represent the largest dimensions of the CLGR and TLGR, respectively. For the CLGRs, $s_c = 10.2\text{ cm}$ is set by the resonator length such that $x_0/s_c = 1.9$. This value of s_c does not include the space between the coupling loop and the resonator. However, as was done with the TLGR, this space could be eliminated by mounting the coupling loop within the bore the resonator. The geometry of the split-TLGRs makes $s_t = 12.7\text{ cm}$ relatively large such that $x_0/s_t = 0.79$ is comparatively small.

Table I compares the figures of merit of various IPT systems reported in the literature. The first observation is that the CLGR system has a figure of merit that is competitive with many of the systems reported in the literature. We note that, because the CLGR resonant frequency is independent of the resonator's length ℓ , it may be possible to increase its figure of merit by decreasing ℓ . An additional increase in x_0/s_c may be expected if the operating frequency could be decreased from 100 MHz to a value closer to 10 MHz that is more typical of IPT systems.

A more striking observation from Table I is that, despite more than a decade of intense research since 2007, the IPT system with the best figure of merit is still the original system reported by the Soljačić group [1]. This realization motivated us to shift our focus away from improving x_0/s and towards designing a resonator with desirable attributes not found among the transmitters and receivers currently used in IPT systems.

Specifically, our focus has been on shaping the electric and magnetic field configurations in and around the transmitter and receiver. As shown earlier in Figs. 3(a) and (c), the electric fields in both the CLGR and TLGR systems are strongly confined to the gap of the resonators. Furthermore, Fig. 3(d) shows that the magnetic field external to the TLGRs is predominantly within the region of space between the transmitter and receiver. Anecdotally, when measuring $|S_{21}|$ as a function of x , we found the CLGR system to be much more sensitive to its surrounding environment. To acquire reliable data, it was necessary to move away from the experimental apparatus before recording the $|S_{21}|$ traces. The peak value of

$|S_{21}|$ changed by several tenths of a decibel when the system was approached to adjust either the coupling loop positions or x . In contrast, the split-TLGR system did not exhibit a sensitivity to similar changes to its surroundings. Therefore, although the CLGR system has more compact resonators, the split-TLGR has the advantage that it is more robust to changing environmental conditions in the neighboring power transfer space.

B. LGR IPT System Characterization

We now present a detailed experimental characterization of the LGR IPT systems. For each transmitter-receiver separation distance x , the source and load coupling loop positions/orientations were tuned to achieve optimal power transfer efficiency. Figures 7 and 8 show example $|S_{11}|$ and $|S_{21}|$ responses measured at different values of x for the CLGR and split-TLGR systems, respectively. Although not shown, we also recorded $|S_{22}|$ and $|S_{12}|$ traces at each value of x . As expected, interchanging the transmitting and receiving resonators had no significant effect on the measured reflection and transmission coefficients.

At the smallest values of x , the coupling k between the transmitting and receiving resonators is strong. To achieve optimal power transfer at a single mode under these conditions, the coupling coefficients k_t and k_r are also required to be large. In the case of the split-TLGRs, we found that for x less than 31 mm, even with the planes of the coupling loops aligned perpendicular to the axis of the bores, we could not obtain k_t and k_r values large enough to observe efficient single-mode power transfer. In this case, the IPT system is said to be overcoupled and exhibits a double resonance [7].

Figure 8(a) is an example of an overcoupled TLGR IPT system at $x = 6.4$ mm. Efficient power transfer is still possible, however, the frequencies of the two normal modes occur above and below the natural resonance frequency of the TLGRs. The low-frequency peak, in which the currents in the two resonators are in phase, is called the even mode while, for the high-frequency odd mode, the currents are out of phase. Note that the peak height of the even mode is slightly higher than that of the odd mode. This phenomenon can be understood in terms of the cross-couplings. In the even mode, the small amount of magnetic flux from the transmitter that couples directly to the load loop adds constructively to the primary contribution from the receiver. In the odd mode, the two sources of flux add destructively [7].

We note that it would be possible to reach smaller values of x without entering into the overcoupled regime by increasing the values of L_s and L_ℓ . This could be done by constructing coupling loops with two or more loops of wire. In the case of the CLGR system, the coupling loops were outside the bore the resonator such that larger-diameter loops could be used. For this reason, the overcoupled regime was avoided in this system, even at the smallest values of x .

When coupling coefficients are tuned for a single mode and x is less than the spatial bandwidth x_0 , the IPT system is critically coupled. In this case, the $|S_{21}|$ frequency response has a single resonance with a broad, flat peak. Figures 7(a)

and (b) show $|S_{21}|$ for a critically coupled CLGR system when $x = 10.8$ mm and 88.8 mm, respectively. Figure 8(b) shows a critically coupled split-TLGR system when $x = 31$ mm. The figures also show the measured $|S_{11}|$ responses. The minimum $|S_{11}|$ values at the resonant frequencies are < -20 dB indicating that very little power is reflected back to the source.

As x is increased and begins to approach the spatial bandwidth x_0 , the coupling k between the transmitter and receiver decreases and k_t and k_r likewise have to be decreased to maintain optimal power transfer. In this regime, the widths of the $|S_{21}|$ resonances narrow and the peak values drop as x is increased. Figures 7(c) and 8(c) show examples of this response for the CLGR and TLGR IPT systems. Finally, for $x > x_0$, the power transfer efficiency drops rapidly and the IPT system is said to be undercoupled. Figure 7(d) shows $|S_{21}|$ for an undercoupled CLGR system.

C. Comparison of Experimental and Simulation Results

Section IV showed EM field simulation results for the IPT systems. The simulations were also used to extract the frequency dependencies of the scattering parameters for various transmitter-receiver separation distances. Figure 9 compares the experimental and simulated $|S_{21}|$ responses. Due to small but unavoidable differences in geometry, the resonant frequencies of the physical LGRs and 3-D models constructed in COMSOL were not identical. Therefore, in Fig. 9 we have plotted the transmission coefficient data as a function of $f/f_p - 1$, where f_p represents the center frequency of the $|S_{21}|$ peak.

Figure 9(a) compares $|S_{21}|$ responses for the CLGR system when $x = 88.8$ mm. The experimental data is identical to the data shown in Fig. 7(b) and has been plotted using $f_{p,e} = 101.04$ MHz. The corresponding simulated transmission coefficient was plotted using $f_{p,s} = 102.41$ MHz. The agreement between the experimental and simulated results is remarkable. Figure 9(b) compares the $|S_{21}|$ frequency sweeps for the TLGR IPT geometry when $x = 31$ mm and using $f_{p,e} = 121.96$ MHz and $f_{p,s} = 122.45$ MHz. The agreement is once again very good, with the simulated system exhibiting slightly less loss at all frequencies.

There are several possible explanations for the small differences observed between the experimental and simulated transmission coefficients. First, in the COMSOL models, it is difficult to precisely replicate the experimental conditions that set the values of k_t and k_r . The simulated coupling loop is perfectly circular and planar whereas the physical structure was handmade and has imperfections. Moreover, one cannot achieve perfect lateral and planar alignment of the coupling loops with the CLGRs on the testbed. In the case of the TLGRs, neither the centering of the coupling loops within the resonator bore nor the setting of the orientations can be done precisely on the testbed. A second consideration is that the simulated scattering parameters were extracted without taking into account losses that occur within the lengths of UT-141 semi-rigid coaxial cable that lead up to the coupling loops. These sections of cable are approximately 15 cm long and are terminated with an SMA connector. In the experimental

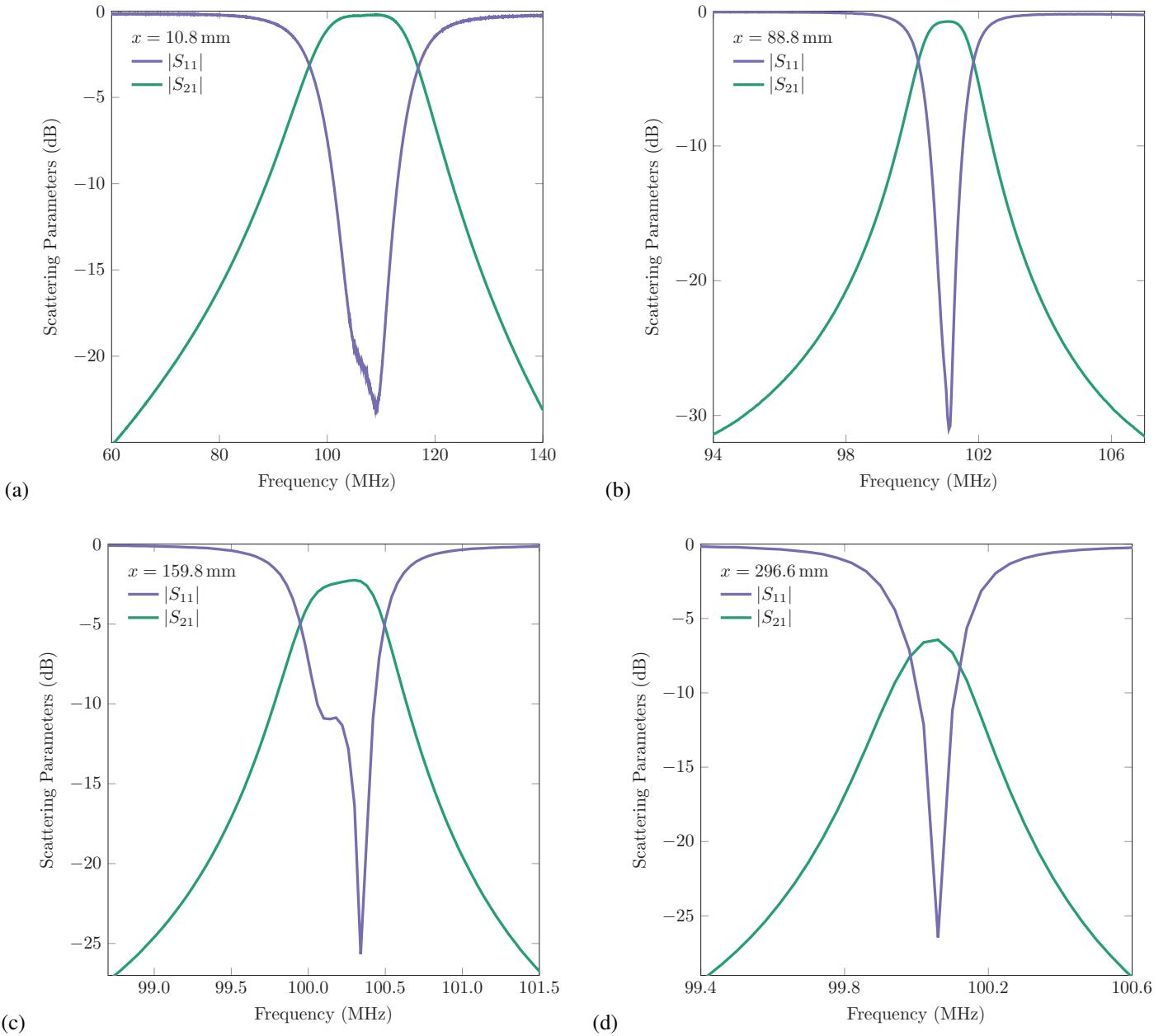


Fig. 7. The $|S_{11}|$ and $|S_{21}|$ responses for the CLGR IPT system for different separation distances. In (a) and (b), $x < x_0$, and the system is critically coupled. In (c), x is close to the -3 dB spatial bandwidth x_0 and the transmission efficiency starts to decrease. In (d), $x > x_0$; the system is undercoupled and significant attenuation is shown in the $|S_{21}|$ response. Note that for all four conditions, the IPT system is matched and the corresponding $|S_{11}|$ is typically better than -25 dB at the resonant frequencies. Also, note the different frequency ranges used in the four plots.

data, the VNA calibration plane is established at the SMA connector and losses that occur along the length of the coaxial cable leading up to the coupling loop are included in the $|S_{21}|$ measurements. Finally, the COMSOL model assumed an aluminum resistivity of $\rho = 2.65 \times 10^{-8} \Omega \text{ m}$ and a lossless dielectric filling the resonator gap. Although these assumptions are reasonable, a small discrepancy in the resistivity and a non-negligible loss tangent in the Teflon dielectric used in the experimental system could lead to observable differences in the transmission coefficients.

D. TLGR Coupling Coefficients k_t and k_r

For all of the x values investigated using the split-TLGRs, after recording the $|S_{21}|$ frequency sweeps, the transmitter and receiver resonators were isolated from one another without changing the orientations of the coupling loops. Next, the VNA was used to measure $|S_{11}|$ of the isolated resonators at both the transmitter and receiver coupling loop ports. Example $|S_{11}|$ responses at three values of x are shown in Figs. 10(a) – (c). In Fig. 10(a), the coupling loops were oriented to achieve maximum coupling such that the resonators, coupled to inductance L_α ($\alpha = s$ or ℓ), were overcoupled. As a result, the values of $|Z|$ at the resonant frequency, determined from

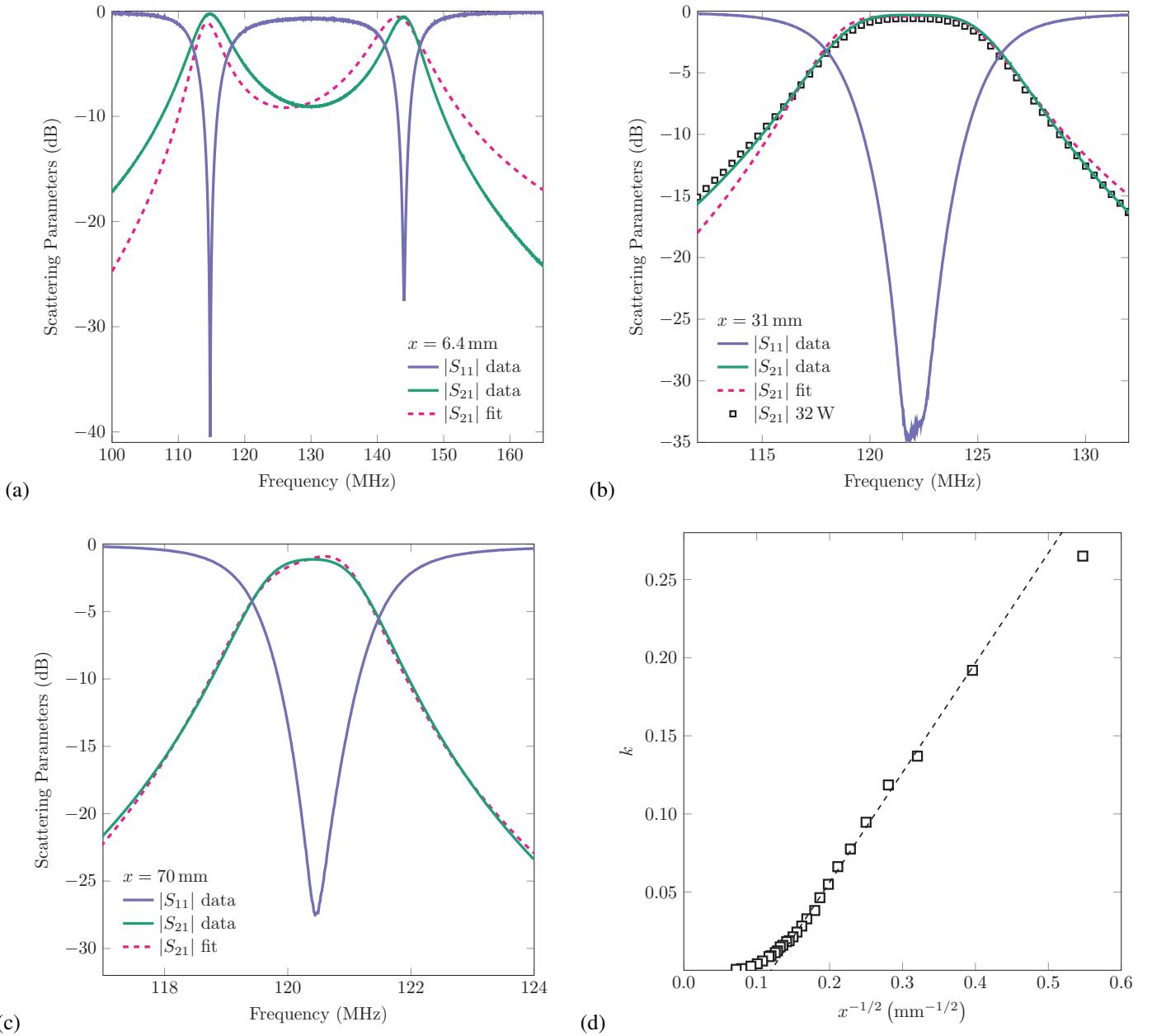


Fig. 8. Fits to the frequency dependence of $|S_{21}|$ for the system of coupled split-TLGRs at various values of the separation distance x . The equivalent circuit of Fig. 1(b) was used to calculate the theoretical $|S_{21}|$ frequency dependence and the fits are used to extract experimental values of the the coupling coefficient k . Although not used in the analysis, for completeness, the $|S_{11}|$ response are also shown. (a) In the $x = 6.4$ mm data, the IPT system is overcoupled and $|S_{21}|$ exhibits a double resonance. (b) At $x = 31$ mm, $|S_{21}|$ has a broad and flat peak and the power transfer efficiency is high. The open square data show a measurement of $|S_{21}|$, made using directional couplers and power sensors, when the IPT system was operated at 32 W. (c) At $x = 70$ mm, the $|S_{21}|$ peak has narrowed and dropped in magnitude. Note that at all values of x , $|S_{11}|$ is typically better than -30 dB at the resonant frequencies. Also, note the differences in the frequency range used for the plots in (a) – (c). (d) The values of k extracted from the fits as a function of $x^{-1/2}$. For small values of x , k approximately follows a $x^{-1/2}$ dependence (dashed line).

(2) and (3), were much greater than $Z_0 = 50 \Omega$ and the $|S_{11}|$ resonances were broad with minima that dipped only a fraction of a decibel below 0 dB. In parts (b) and (c) of Fig. 10, the coupling loops were rotated away from maximum coupling and the $|S_{11}|$ resonances sharpened and exhibited deeper minima. For the split-TLGR IPT system, optimal power transfer was acheived with the transmitter resonator slightly more strongly coupled to L_α than the receiver resonator. The $|S_{11}|$ data were fit to (1) – (3) based on the circuit model developed in Section II-A.

The loop inductances L_s and L_ℓ were determined from separate reflection coefficient measurements made after isolating the coupling loops from the TLGRs [41]. The values obtained for the source and load loops were $L_s = (66.1 \pm 0.1)$ nH and $L_\ell = (65.5 \pm 0.1)$ nH, respectively. These measurements were compared to estimates made using an empirical expression for the inductance of a loop of wire

$$L_\alpha \approx \mu_0 r \left[\ln \left(\frac{8r}{a} \right) - 2 \right]. \quad (13)$$

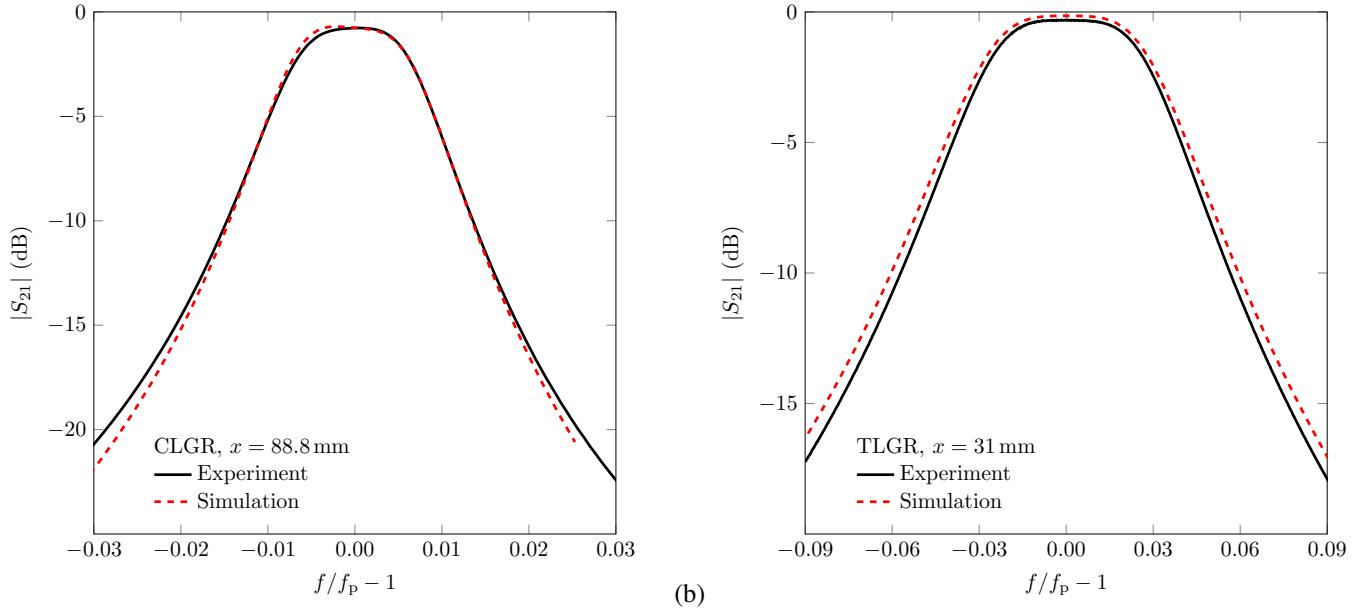


Fig. 9. Comparison of $|S_{21}|$ measured experimentally and extracted from COMSOL simulations. (a) The CLGR IPT system when $x = 88.8$ mm. (b) The TLGR IPT system when $x = 31$ mm. For comparison purposes, horizontal axes of $f/f_p - 1$ were chosen so as to place the center of the $|S_{21}|$ peaks at zero.

In this expression, r is the loop radius and a is the radius of the wire [47], [48]. Using $r = 15$ mm and $a = 0.465$ mm for our coupling loops made from UT-141 semi-rigid coaxial cable, (13) gives an inductance of 67.0 nH which is reasonably consistent with the experimental results.

The $|S_{11}|$ fits are all very good and the extracted parameters include the unloaded resonant frequencies f_β and quality factors Q_β of the transmitter and receiver LGRs as well as the coupling coefficients k_t and k_r . An offset parameter was also included in the fit to account for the fact that, away from resonance, the $|S_{11}|$ curves do not reach 0 dB. This effect is most clearly shown in Figs. 10(a) and (b) and is likely due to losses along the lengths of the coaxial cables that lead up to the coupling loops.

Table II summarizes the parameters extracted from the $|S_{11}|$ fits shown in Fig. 10. For the transmitter, the f_t fit values were between 119.6 and 120.1 MHz and Q_t varied from 850 to 1200. For the receiver we found a similar range of values for f_r ; however, the quality factor was found to be slightly lower with $620 < Q < 850$. Plots of the x -dependencies of k_r and k_t are shown in Fig. 10(d). For $x \lesssim 31$ mm, the coupling loops were oriented parallel to the cross-section of the split-TLGR bore and k_t and k_r reached their maximum values. As discussed in Section IV, a substantial fraction of the total magnetic flux is contained within the resonator gap. This observation explains why the maximum values of k_t and k_r , being about 0.29, are significantly less than one. For $x > 31$ mm, k_t and k_r decrease with increasing x . For the transmitting side, we found $k_t \propto x^{-0.71}$ and for the receiving side $k_r \propto x^{-0.99}$.

E. TLGR Coupling Coefficients k

With all of L_s , L_ℓ , f_t , f_r , Q_t , Q_r , k_t , and k_r known, the system of equations (6) – (9) can be solved for I_r and

TABLE II
TGLR PARAMETERS ASSOCIATED WITH THE $|S_{21}|$ AND $|S_{11}|$ FITS SHOWN IN FIGS. 8 AND 10

Isolated Transmitter $ S_{11} $, Fig. 10				
	$L_s = 66.1$ nH, $L_t = 8.65$ nH			
x (mm)	6.4	31	70	118
k_t	0.290	0.287	0.168	0.125
f_t (MHz)	119.73	120.09	119.58	119.607
Q_t	1020	1010	882	877
offset	0.018	0.017	0.010	0.009
Isolated Receiver $ S_{11} $, Fig. 10				
	$L_\ell = 65.5$ nH, $L_r = 8.65$ nH			
x (mm)	6.4	31	70	118
k_r	0.282	0.285	0.1314	0.0790
f_r (MHz)	119.60	119.79	119.90	119.930
Q_r	850	740	618	680
offset	0.015	0.012	0.008	0.008
Coupled Transmitter/Receiver IPT $ S_{21} $, Fig. 8				
	$L_s = 66.1$ nH, $L_t = 8.65$ nH			
x (mm)	6.4	31	70	118
k	0.192	0.0383	0.0093	0.0026
b_t	1.083	1.004	0.996	0.999
b_r	0.989	0.983	1.002	1.000

the only unknown parameters in $|S_{21}| = 2 |I_\ell/V_s| Z_0$ are the TLGR inductances, L_t and L_r , and the coupling coefficient k . The effective inductance of a complete TLGR was calculated in [43]. Assuming that the magnetic fields outside the bore are negligible, the split-TLGR has twice the inductance of a full TLGR such that

$$L_\beta \approx 2\mu_0 r_1 \left[1 - \sqrt{1 - \left(\frac{r_0}{r_1} \right)^2} \right]. \quad (14)$$

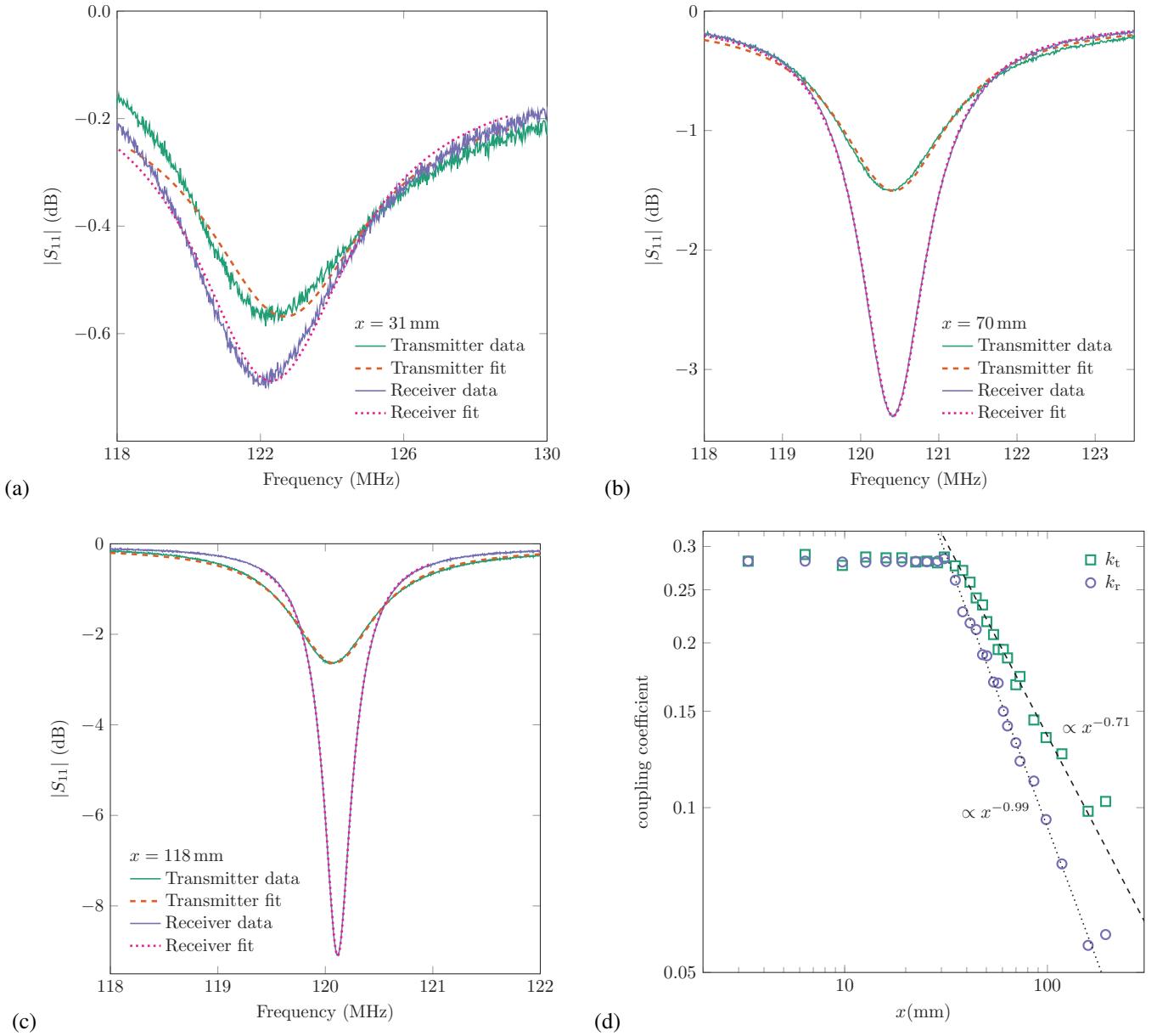


Fig. 10. Fits to the frequency dependence of $|S_{11}|$ for isolated ($k \rightarrow 0$) split-TLGRs. The theoretical model for $|S_{11}|$ was generated using the equivalent circuit shown in Fig. 1(a) and the fits were used to extract values of the coupling coefficients k_t and k_r . We show the fits for the transmitter and receiver when (a) $x = 31$ mm, (b) $x = 70$ mm, and (c) $x = 118$ mm. (d) The extracted values of k_t and k_r as a function of x . For $x \leq 31$ mm the coupling loops were oriented to achieve the maximum possible coupling and, therefore, k_t and k_r do not change over these separation distances. Above $x = 31$ mm, in order to maintain optimal power transfer efficiency, the coupling to the transmitting and receiving LGRs had to be decreased as x was increased. The dashed and dotted lines are proportional to $x^{-0.71}$ and $x^{-0.99}$, respectively.

Using the dimensions in Fig. 2(c), (14) gives $L = 8.65$ nH which was the value assumed for both L_t and L_r . We found that the quality of the fits were very sensitive to the values of f_t and f_r . To ensure high-quality fits, we introduced additional fitting parameters b_t and b_r to scale the values of f_t and f_r , respectively. On average, the scaling factors changed f_t and f_r by only 1.6 % and 0.8 %, respectively.

The fits to $|S_{21}|$ measurements are generally good and examples are shown in Fig. 8(a) – (c). The fit function underestimates the measured data below f_0 and overestimates it above f_0 . The mismatch between the theoretical model and experimental data becomes more exaggerated as x is

decreased. These same features were observed in the analysis by Sample *et al.* in [7]. Those authors improved the quality of their fits by introducing two more fit parameters to account for the cross-couplings between the source loop and receiver and between the load loop and transmitter. We have not included cross-couplings in our analysis. The additional fit parameters will undoubtedly improve the quality of the fit, however, it is not clear that it results in more reliable values for the coupling coefficient k . Furthermore, one would always expect the circuit models to have some deficiencies due to the fact that the transmitter and receiver resonators, whatever their geometry, are not lumped-element *LRC* circuits.

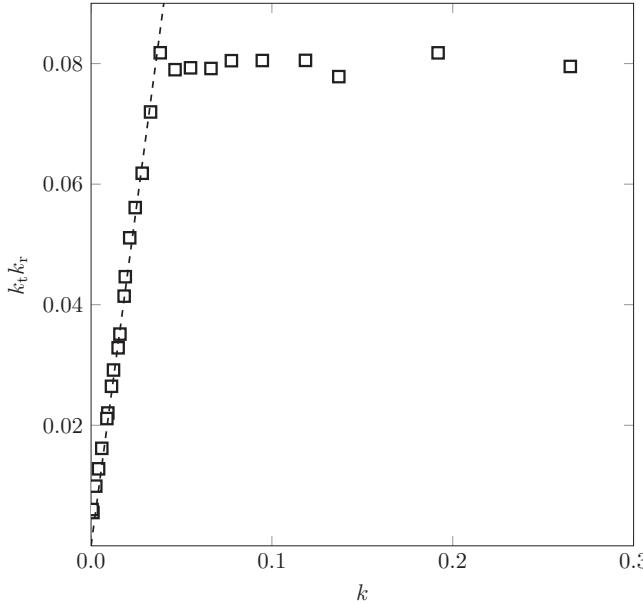


Fig. 11. The product $k_t k_r$ as a function of k . For weak coupling ($k \lesssim 0.04$), optimal power transfer efficiency corresponds to the condition that the $k_t k_r$ product is proportional to k . The dashed line is $k_t k_r = 2.24k$. When $k \gtrsim 0.04$ (corresponding to $x < 31$ mm), the $k_t k_r$ value saturates as both the source and load coupling loops are already oriented to achieve maximum coupling.

The x -dependence of k , determined from the $|S_{21}|$ fits, is shown in Fig. 8(d). The data are plotted as a function of $x^{-1/2}$ to highlight that, in the strong coupling limit (small x), $k \propto x^{-1/2}$. In the overcoupled regime, where $|S_{21}|$ splits into a double resonance, the coupling coefficient k can also be estimated using

$$k = \frac{f_2^2 - f_1^2}{f_2^2 + f_1^2}, \quad (15)$$

where f_1 and f_2 are the resonant frequencies of the even and odd modes, respectively [49]. For the $x = 6.4$ mm data shown in Fig. 8(a), (15) gives $k \approx 0.22$ which is in reasonably good agreement with 0.192 obtained from the fit.

Many authors have shown that four-coil IPT systems achieve optimal power transfer efficiency when the coupling coefficients are tuned such that $k \propto k_t k_r$ [4], [7], [9], [11]. Figure 11 shows a plot of $k_t k_r$ as a function of k for the split-TLGR system based on the $|S_{11}|$ and $|S_{21}|$ analyses described in Sections V-D and V-E, respectively. For weak coupling, before k_t and k_r have reached their maximum values, the linear relation between the $k_t k_r$ product and the coupling coefficient k is clearly observed.

With all of the TLGR IPT system parameters known (Table II), the equivalent circuit model of Fig. 1(b) can be used to calculate the currents in transmit and receive resonators. At a frequency of 121 MHz, we found $|I_t| = |I_r| = 262$ mA. From Ampère's law, the magnetic field strength at the inner radius of the split-TLGR bore is given by $B = \mu_0 |I_\beta| / [\pi (r_1 - r_0)] = 3.7 \mu\text{T}$ which is in reasonably good agreement with the simulation result of 3.2 μT shown in Fig. 4(b). An estimate of the electric field strength can be made by calculating the voltage across the gap and then dividing by

the gap height: $E = |I_\beta| / (\omega C_\beta t) = I_\beta \omega_\beta^2 L_\beta / (\omega t)$, where $\omega_\beta^2 = 1 / (L_\beta C_\beta)$. At 121 MHz, the result is $E = 17$ kV/m which is again in reasonable agreement with the simulation result of 15 kV/m.

F. CLGR and TLGR IPT System Bandwidths

To produce the plots of peak $|S_{21}|$ versus x shown in Fig. 6 for the CLGR and split-TLGR systems, the coupling loop positions/orientations were tuned to optimize the power transfer efficiency at each value of x . A drawback of this approach is that the frequency of peak power transfer efficiency f_p varies with x . The data points in Figs. 12(a) and (b) show the x -dependencies of the peak frequency for the CLGR and split-TLGR systems. Excluding the overcoupled region of the TLGR data, f_p was found to be a nearly linear function of x^{-1} for both systems when $x < x_0$. Because low-frequency ISM bands are typically only tens of kilohertz wide, practical IPT systems are restricted to narrow bandwidths limiting the application of frequency agile sources. Therefore, the performance under fixed-frequency source conditions was evaluated.

The green vertical bars in Fig. 12 represent the range of frequencies for which $|S_{21}|$ is within 0.458 dB of its peak value, or the power transfer efficiency is no worse than 90% of the optimal efficiency. For example, the $x = 31$ mm data shown in Fig. 8(b) have a maximum $|S_{21}|$ value of -0.306 dB at 122.0 MHz. $|S_{21}|$ drops to -0.764 dB at 119.7 and 124.3 MHz which defines the bandwidth spanned by the vertical green bar in Fig. 12(b). This bandwidth shrinks as x increases. For example, the $x = 70$ mm data shown in Fig. 8(c) have a bandwidth of 0.91 MHz which is only 20% of the bandwidth at $x = 31$ mm. Once $x > x_0$, the bandwidth rapidly shrinks for both the CLGR and split-TLGR systems. The orange bars show the bandwidth at different x when $|S_{21}|$ is required to be within 0.223 dB of its peak value, which corresponds to a power transfer efficiency that is no worse than 95% of peak efficiency.

The most striking difference between Figs. 12(a) and (b) is the x -dependence of the lower-limit of the bandwidth. For the CLGR, both the upper and lower limits of the bandwidth decrease approximately linearly with x^{-1} . As a result, there is no fixed frequency that will maintain high power-transfer efficiency for a wide range of x -values. For the split-TLGR system, while the upper limit of the bandwidth does vary linearly with x^{-1} , the lower limit remains nearly constant for $x > 31$ mm. This property of the split-TLGR system was unexpected and shows that efficient power transfer can be obtained at a fixed frequency over a wide range of x values. The horizontal region shaded gray in Fig. 12(b) highlights the range of frequencies, 0.4 MHz wide, that is always within 0.458 dB of the peak $|S_{21}|$ when $22 \leq x \leq 100$ mm. The yellow bar defines the band of frequencies, 0.1 MHz wide, for which $|S_{21}|$ is always within 0.223 dB of the peak value when $25 \leq x \leq 100$ mm. As discussed in Section V-B, the lower limit of the x ranges could be extended by increasing L_s and L_ℓ so as to avoid the frequency splitting associated with overcoupled IPT systems.

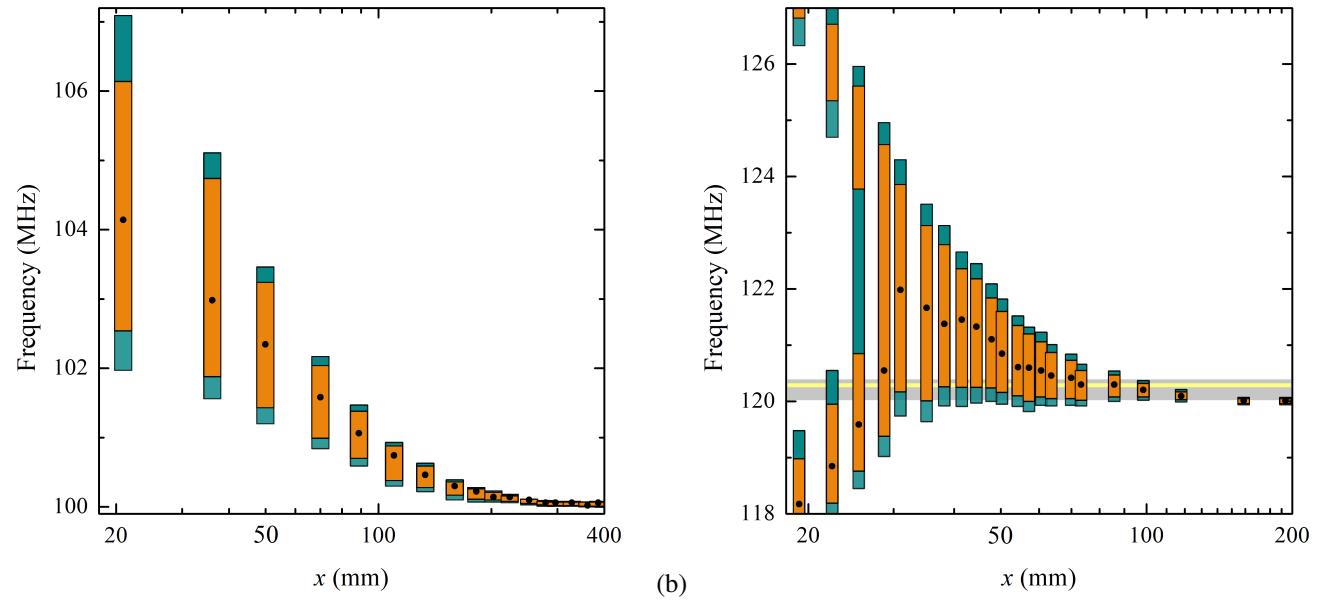


Fig. 12. Bandwidth analysis of the LGR IPT systems versus separation distance x . The dots show the frequency of peak $|S_{21}|$ as a function of x . The orange (green) bars represent the range of frequencies for which $|S_{21}|$ is within 0.22 dB (0.46 dB) of its peak value. (a) For the CLGR system, the top and bottom ends of the 0.22 and 0.46 dB frequency ranges both change with x . (b) For the TLGR system the bottom ends of the frequency ranges are approximately constant when $x > 31$ mm. As a result, there exists a band of frequencies for which $|S_{21}|$ remains close to the peak value as x is varied. The horizontal grey bar, 0.4 MHz wide, represents the band of frequencies for which $|S_{21}|$ is always within 0.46 dB of its peak value when $22 \leq x \leq 100$ mm. The yellow bar, 0.1 MHz wide, shows the bandwidth for the 0.22 dB case when $25 \leq x \leq 100$ mm.

G. Operation of the TLGR IPT System at 32 W

All of the measurements described up to this point were taken using a VNA that supplies -17 dBm ($20\ \mu\text{W}$) of source power. We now present a characterization of the split-TLGR IPT system at 45 dBm (32 W). The source signal was supplied by a Rhode & Schwarz SMY02 signal generator followed by a Mini-Circuits LZY-22+ power amplifier. To measure the forward power from the amplifier, a OSR Broadcast Research C21A8 directional coupler, with a coupling of 40 dB, was inserted between the amplifier and the source coupling loop. The load loop was terminated by a $50\ \Omega$ load with a 100 W power rating. A second directional coupler was used to measure the power delivered to the load. The incident power P_0 and transmitted power P_L were monitored using a Keysight E4417A dual-channel power meter paired with Keysight E9320 power sensors. A simple LabVIEW program was written to step through a range of frequencies and record P_0 , P_L , and $|S_{21}| = 10 \log(P_L/P_0)$ in decibels.

Measurements were taken at six different values of x between 6 and 80 mm. For each separation distance, the coupling loop orientations were first optimized using the VNA before completing frequency sweeps at higher power. For all six values of x , the VNA and high-power $|S_{21}|$ measurements were in good agreement. The small discrepancies that were observed are attributed to directional coupler insertion loss and imperfect power sensor calibrations. Figure 8(b) shows an overlay of the high-power and VNA $|S_{21}|$ measurements for the critically-coupled case when $x = 31$ mm. The most significant difference between the two data sets is the peak value of $|S_{21}|$. The high-power data reach a maximum of -0.598 dB compared to -0.306 dB for the VNA data.

VI. DISCUSSION

The IPT system using CLGRs as transmitter and receiver resulted in a large spatial bandwidth x_0 and a competitive figure of merit x_0/s . Therefore, this system is well suited to applications which require large separations between the transmitter and receiver. The CLGR system strongly confines electric fields within the gap of the resonator thereby desensitizing the power transfer efficiency to the presence of extraneous dielectric objects. The magnetic fields, on the other hand, occupy the entire volume of space surrounding the CLGRs which enables some degree of omnidirectional IPT.

The system characterized in this work operated at a 100 MHz. Reducing the resonant frequency by either increasing d_c or inserting a high- ϵ_r and low-loss dielectric in the gap, would increase the ratio λ/d_c and diminish radiative losses such that an enhancement of the figure of merit would be expected.

It is worth pointing out that changing the length of the CLGRs has only a small effect on the resonant frequency [42]. Therefore, it is possible to select the CLGR transmitter length that produces the desired magnetic field profile outside the resonator. For example, a short CLGR could be used to produce magnetic fields patterns similar to those generated by helical and spiral resonators.

Although the figure of merit of the split-TLGR IPT system was low compared to that of the CLGR system, it has other practical advantages that make it an attractive option for some applications. For example, the system can be operated efficiently at a fixed frequency for a wide range of transmitter-receiver distances and the unique geometry offers a way to manipulate the spatial distribution of the magnetic fields. In particular, the magnetic field strength everywhere outside the

resonators, excluding the region of space directly between the transmitter and receiver, is very low. These features have the potential to make the system a good choice for some specialized applications in which the lateral alignment of the transmitter and receiver can be maintained.

For example, because the electric and magnetic fields of the split-TLGR system are restricted to only a few well-defined regions of space, various insulating and conducting objects can be situated nearby the resonators without adversely affecting the power transfer efficiency. Lossy dielectrics can be placed anywhere except within the narrow gap of resonator. Conducting objects can likewise be located anywhere except within the volumes of space that connect the bores of the transmit and receive resonators. A possible application is IPT through a slab of concrete embedded with reinforcing steel (rebar). As long as the rebar does not pass through the volumes of space connecting the transmitter and receiver bores, efficient energy exchange is possible. Other IPT designs, with magnetic fields that occupy the entire volume of space surrounding the resonators, would suffer losses due to eddy currents induced in the steel bars. A similar application would be efficient IPT through a wall that has plumbing, duct work, and/or electrical conduits running parallel to its surfaces.

As discussed in Section III, the electric field confinement provided by LGRs make them good candidates for IPT applications in saltwater. Even with the electric fields isolated from the conducting medium, a magnetic power dissipation proportional to $\sigma\omega_0^2 B^2$ will limit the power transfer efficiency [46]. If the conducting medium is excluded from LGR bores using seals or another means, the magnetic power dissipation will be due only to the fields outside the resonators. In the case of the split-TLGRs, the external fields are only substantial between the transmitter and receiver such that losses associated with the conducting medium outside of this region would be negligible. Low-frequency split-TLGRs could be used, for example, to wirelessly recharge autonomous underwater vehicles (AUVs) at a charging base beneath the ocean or sea surface.

VII. CONCLUSIONS

We have implemented efficient IPT systems that operate near 100 MHz using inductively-coupled LGR transmitters and receivers. The LGRs are high- Q structures that are small in size compared to the free-space wavelength at resonance. With a constraint on the maximum size of the resonators, our designs minimize the resonance frequency. Impedance matching is achieved by relatively simple adjustments to the position/orientation of source and load coupling loops. Lumped-element equivalent circuits were used to develop theoretical models that could be fit to measured scattering parameters and used to extract the three relevant coupling coefficients.

We designed and investigated IPT systems using both CLGRs and split-TLGRs. Although the CLGR system allowed for efficient power transfer at greater separation distances between transmitter and receiver, the split-TLGR system offered two significant advantages: (1) there exists an operating bandwidth for near-optimal power transfer that spans a wide

range of transmitter-receiver separation distances and (2) there is minimal external magnetic flux outside of the region directly between the transmitter and receiver making the system insensitive to the surrounding environment.

With the source and load coupling loop orientations tuned to achieve maximum power transfer, the transmitter and receiver TLGRs were isolated from one another and fits to the frequency dependence of $|S_{11}|$ were used to determine k_t and k_r . Even with the loop orientations set to achieve maximum coupling, the largest coupling coefficients obtained were only 0.29. COMSOL simulations showed the presence of substantial magnetic flux within the gap of the TLGRs which explains why coupling loops suspended within the bore of the resonator are not able to achieve stronger couplings.

Using the experimentally-determined values of k_t and k_r , fits to the frequency dependence of $|S_{21}|$ were used to extract the coupling coefficient k between transmitter and receiver. At strong coupling (small x), k followed a $x^{-1/2}$ dependence. Furthermore, as predicted by equivalent circuit models, we found that optimal power transfer is achieved when the condition $k_t k_r \propto k$ is satisfied.

In future work, we plan to operate the LGR-based IPT designs at lower frequencies. One approach to lower the frequency is to insert high- ϵ_r and low-loss dielectrics within the gap of the resonators. We will also investigate IPT through a conducting medium, such as saltwater, using LGR transmitters and receivers.

ACKNOWLEDGMENT

We thank NSERC for providing funding for this project and we are grateful for the fabrication of the LGRs by the UBC Okanagan machine shop.

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